

Summary of Stability Classification

Asymptotically stable – All trajectories of its solutions converge to the critical point as $t \rightarrow \infty$. A critical point is asymptotically stable if all of A 's eigenvalues are negative, or have negative real part for complex eigenvalues.

Unstable – All trajectories (or all but a few, in the case of a saddle point) start out at the critical point at $t \rightarrow -\infty$, then move away to infinitely distant out as $t \rightarrow \infty$. A critical point is unstable if at least one of A 's eigenvalues is positive, or has positive real part for complex eigenvalues.

Stable (or neutrally stable) – Each trajectory move about the critical point within a finite range of distance. It never moves out to infinitely distant, nor (unlike in the case of asymptotically stable) does it ever go to the critical point. A critical point is stable if A 's eigenvalues are purely imaginary.

In short, as t increases, if all (or almost all) trajectories

1. converge to the critical point \rightarrow **asymptotically stable**,
2. move away from the critical point to infinitely far away \rightarrow **unstable**,
3. stay in a fixed orbit within a finite (i.e., bounded) range of distance away from the critical point \rightarrow **stable (or neutrally stable)**.

$(0,0)$ - disease-free equilibrium

$$J = \begin{bmatrix} \beta_H - (\delta_H + d_H) & 0 \\ 0 & \beta_C - (\delta_C + d_C) \end{bmatrix}$$

Aby p. być asymptotycznie stabilny wartości własne muszą być ujemne. Aby wartości własne macierzy 2×2 były ujemne - ślad macierzy < 0 , wyznacznik > 0 .

$$\begin{cases} \beta_H - (\delta_H + d_H) + \beta_C - (\delta_C + d_C) < 0 & (\text{ślad macierzy}) \\ (\beta_H - (\delta_H + d_H)) \cdot (\beta_C - (\delta_C + d_C)) > 0 & (\text{wyznacznik}) \end{cases}$$

$$\beta_H - (\delta_H + d_H) = a$$

$$\beta_C - (\delta_C + d_C) = b$$

$$\begin{cases} a + b < 0 \\ a \cdot b > 0 \end{cases} \Rightarrow a > 0 \wedge b > 0 \quad \vee \quad \underline{\underline{a < 0 \wedge b < 0}}$$

$$\beta_H - (\delta_H + d_H) < 0 \quad \wedge \quad \beta_C - (\delta_C + d_C) < 0$$

$$\frac{\beta_H}{\delta_H + d_H} < 1 \quad | \cdot \frac{\Lambda}{\delta_S N}$$

$$\frac{\beta_C}{\delta_C + d_C} < 1 \quad | \cdot \frac{\Lambda}{\delta_S N}$$

$$\frac{\beta_H \Lambda}{(\delta_H + d_H) \delta_S N} < \frac{\Lambda}{\delta_S N}$$

$$\frac{\beta_C \Lambda}{(\delta_C + d_C) \delta_S N} < \frac{\Lambda}{\delta_S N}$$

$$\underline{\underline{R_H < \frac{\Lambda}{\delta_S N}}}$$

$$\underline{\underline{R_C < \frac{\Lambda}{\delta_S N}}}$$